


# AUTOPILOT



PuzzleBot needs to use its autopiloting system to run some errands, but it is missing something important. Its processors know the steps required to get to each destination, but the order is jumbled in its memory. To make matters worse, its autopilot was programmed by a Roomba!


PuzzleBot drives straight until it crashes into a wall or obstacle, at which point it **stops** and changes direction 90°, repeating the process until reaching its destination... even if it's not taking the most efficient route. At the start of each trip PuzzleBot's sensors are fine, but **after each crash**, they **shift incrementally more** out of sync.


Help PuzzleBot find its way to each X and recover something that will make its next trip even better!

C	A	O	R	C	V
G	E	N	D	F	C
	E	S		C	Z
I		L	R	K	I
Z	N	P	N	B	O
X	M	P	A		

STEPS  
NORTH  
SOUTH  
SOUTH  
EAST  
EAST  
WEST

STEPS  
NORTH  
SOUTH  
SOUTH  
EAST  
EAST  
WEST

A	L	N	Y	R	E
I	M	P	N	J	
Y	U	M	I	V	X
	O		N		H
M	K	V	E	E	U
A	R	C	O	C	T

F		L	I	N	N
M	N		A		R
S	B	B	E	T	I
L	R	C	S	M	O
D	Y	K	R	P	D
	O	N	X	X	T

STEPS  
NORTH  
SOUTH  
SOUTH  
EAST  
EAST  
WEST  
WEST

